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5. This geometrical algorithm may easily be translated into an algebraical algorithm and thus furnish an elementary arithmetical method of extracting roots by a method of very rapid convergence. The general algorithm thus obtained is as follows :

$$\frac{x_1}{y_1} = \frac{(n-1)x^n + y^n z + nxyz^{n-1}}{nx^{n-1}y + x^n + (n-1)y^n z}, \quad (1)$$

where  $n$  denotes degree of root,  $z$  the given number, the root of which is to be found,  $x \div y$  an arbitrary initial value and  $x_1 \div y_1$  the succeeding corrected value.

By dividing the right side of (1) by  $y^n$  and substituting  $a$  for  $x \div y$ , and  $a_1$  for  $x_1 \div y_1$  we obtain another form of the same algorithm :

$$a_1 = \frac{(n-1)a^n + z + naz}{na^{n-1} + a^n + (n-1)z} \quad (2.)$$

In regard to this algorithm the following observation may be allowed. There are the two following algorithms of a more simple form, i. e.

$$a_1 = \frac{(n-1)a^n + z}{na^{n-1}} \quad (3,) \quad \text{and} \quad a_1 = \frac{naz}{a^n + (n-1)z} \quad (4.)$$

If  $a$  be again an arbitrary approximate value for the  $n^{\text{th}}$  root of  $z$ , then the corrected value  $a_1$  in (3) always furnishes a value greater than the  $n^{\text{th}}$  root of  $z$ ; and the value in (4) always is smaller than the  $n^{\text{th}}$  root of  $z$ . The acceleration of both methods is of the same (quadratic) order. Now by adding both numerators and dividing by the sum of both denominators we obtain a mean value between the two in (3) and (4); that is, another approximate value for the  $n^{\text{th}}$  root of  $z$  of at least the same degree of approximation. But this result exactly coincides with the algorithm under (2), derived from geometrical constructions.

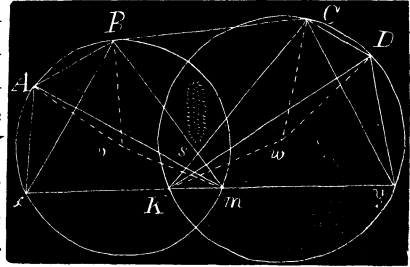
## SOLUTION OF A PROBLEM IN SURVEYING.

BY T. J. LOWRY, U. S. C. S. SAN FRANCISCO, CAL.

*Problem*:—Four points in the same plane being given in position to determine the position of any other two intervisible points (or places of observation) in reference to these points, having from each place of observation the angles included between the other place of observation and each of two of the known points, and with the known points so situated that the two which are visible from the first point of observation are not visible from the second, and *vice versa*.

Let  $A, B, C$  and  $D$  be the four given points, and  $\angle AxB, \angle Bxy, \angle Cyx$  and  $\angle CyD$  be the observed angles.

In the  $\triangle ABm$  are given  $AB$ , and the  $\angle ABm$  (= supplement of the sum of the observed  $\angle s \angle AxB$  and  $\angle Bxy$ ), and the  $\angle BmA$  (= observed  $\angle AxB$ ), we can hence find  $Bm$ . And in  $\triangle DCK$  are known  $CD$ , and the  $\angle DCK$  (= supplement of the sum of the observed  $\angle s \angle DyC$  and  $\angle Cyx$ ), and the  $\angle CKD$  (= observed  $\angle CyD$ ) to find  $CK$ .



Now the  $\angle SBC = \angle ABC - \angle ABm$ , and  $\angle SCB = \angle BCD - \angle DCK$ .  $\therefore$  in  $\triangle BSC$  we have  $BC$  and all the angles to find  $BS$  and  $SC$ . But  $mS = Bm - BS$ , and  $KS = KC - SC$  and the  $\angle KSm = \angle BSC$ .  $\therefore$  in  $\triangle SKm$  are known two sides  $SK$  and  $mS$  and the included angle, to find angles  $\angle SmK$  and  $\angle SKm$ . Now in  $\triangle Bmx$  are given  $Bm$ , and the  $\angle s \angle Bmx$  and  $\angle Bxm$  to get  $Bx$ . And then in  $\triangle ABx$  we have  $Bx$ , and  $AB$  and the  $\angle AxB$  to determine  $Ax$ . Also in  $\triangle KCy$  are given  $KC$ , and  $\angle s \angle CKy$  and  $\angle CyK$  to find  $Cy$ . Then in  $\triangle CyD$  are known  $Cy$ ,  $CD$  and the  $\angle CyD$  to get  $Dy$ .

Since the  $\angle s \angle wDC$  and  $\angle wCD$  are each equal to the complement of the observed  $\angle DyC$  the rule for laying down the circle of position through  $C$  and  $D$  is obviously to lay off from  $CD$  at the points  $C$  and  $D$  the complement of the observed  $\angle CyD$  and the point of intersection of the produced sides of these  $\angle s$  will be the center of a circle of position. Now about this point with radius  $Cw$  (or  $Dw$ ) sweep the circle of position; and in like manner lay down the other circle of position through  $A$  and  $B$ . Then lay off from  $Cw$  at the point  $w$  twice the observed  $\angle Cyx$  and produce the side  $wK$  till it intersects the first circle of position in some point as  $K$  (which will be a point in the line of sight through  $x$  and  $y$ ): also from  $Bv$  at the point  $v$  lay off twice the observed angle  $\angle Bxy$  and the point  $m$  where the side  $vm$  produced intersects the second circle of position will be another point in the line joining  $x$  and  $y$ . Now through  $K$  and  $m$  draw a right line and produce it each way until it intersects the circle of position and the points of intersection  $x$  and  $y$  will be the required places of observation.

But with the aid of the "three arm Protractor" this problem can be plotted much more expeditiously (and without laying down circles of position) as follows:—with the  $\angle s \angle ABx$ , and  $\angle Bxy$  set off respectively on the left and right limbs of the protractor, cause the fiducial edges of the left and middle arms to traverse  $A$ , and  $B$ , and draw a line along the true edge of its right

arm, then shift the center of the protractor (taking care to keep the true edge of the left and middle arms bisecting the points  $A$  and  $B$ ) and draw another line along the true edge of the right arm and the point of intersection of the two lines thus drawn will be a point in the line of sight joining  $x$  and  $y$ . Now with the  $\angle s DyC$  and  $Oyx$  set off on the right and left limbs of the protractor, shift its center till the true edges of the right, middle and left arms traverse  $D$ ,  $C$  and  $K$ , dot the center and we have  $y$  (one of the places of observation). And again with the  $\angle s AxB$  and  $Bxy$  on the left and right limbs, place the true edge of the right hand arm on the line  $Kmy$  and shift the center along this line till  $A$  and  $B$  are traversed by the true edges of left and middle arms then dot the center and you have  $x$  (the other place of observation).

The Hydrographer, the Topographer and the Explorer will each find this problem servicable.

## ODD NUMBERS AND EVEN NUMBERS.

BY ARTEMAS MARTIN, ERIE, PA.

All numbers are either odd or even. An *even* number is a number that can be divided by 2 without a remainder; an *odd* number is one that is not divisible by 2. 1, 3, 5, 7, are *odd* numbers; 2, 4, 6, 8, are *even* numbers.

All even numbers are comprised in the formula  $2n$ , and all odd numbers in either of the formulæ  $2n + 1$ ,  $2n - 1$ .

*Proposition I.* — The sum of two even numbers is even.

*Proof.* — Let  $2m$  and  $2n$  represent any two even numbers; their sum is  $2m + 2n = 2(m + n)$ , which is even.

*Prop. II.* — The sum of two odd numbers is even.

*Proof.* — Let  $2m + 1$  and  $2n + 1$  be any two odd numbers; their sum is  $2m + 1 + 2n + 1 = 2m + 2n + 2 = 2(m + n + 1)$ .

*Prop. III.* — The sum of an odd number and an even number is odd.

*Proof.* — Let  $2m + 1$  be any odd number and  $2n$  any even number; then  $2m + 1 + 2n = 2(m + n) + 1$ , which is odd.

*Prop. IV.* — The difference of two even numbers is even.

*Proof.* —  $2m - 2n = 2(m - n)$ .

*Prop. V.* — The difference of two odd numbers is even.

*Proof.* —  $2m + 1 - 2n - 1 = 2(m - n)$ .

*Prop. VI.* — The difference of an odd number and an even one is odd.

*Proof.* —  $2m + 1 - 2n = 2(m - n) + 1$ .